Multifidelity Monte Carlo Methods for Uncertainty Quantification

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# Multifidelity models and multifidelity methods

What are they and why use them?

# Multifidelity models

covering a range of different resolutions, scales, modeling assumptions, etc.

simplified physics, loosened tolerance, coarse grid, data-fit, projection-based ROM, etc.  high-fidelity model ("truth") mapping input *z* to output *y*

 $f^{(1)}: \mathcal{Z} \to \mathcal{Y}$ 

*k* – 1 lower-fidelity models mapping input *z* to output *y*

$$f^{(2)}, \dots, f^{(k)} \colon \mathcal{Z} \to \mathcal{Y}$$

$$Z f^{(1)} Y$$



- model  $f^{(i)}$  has cost  $w_i$
- model  $f^{(i)}$  has fidelity  $f_i$
- models do not necessarily form a hierarchy

#### Multifidelity methods

#### for outer-loop problems



- **Outer-loop**: computational applications that form outer loops around a model
  - overall outer-loop result is obtained at the termination of the outer loop
  - examples: optimization, uncertainty propagation, inverse problems, data assimilation, control, sensitivity analysis
- **Multifidelity methods**: goal is to solve the outer-loop problem at high fidelity
  - invoke multiple models to reduce computational cost
  - maintains guarantees on outer-loop result
- Key questions
  - how to combine model estimates?
  - how to balance evaluations among models?
  - how to guarantee outer-loop result?



# Multifidelity strategies

examples of multifidelity strategies for the outer loop



- optimization Alexandrov & Lewis, 1999; Eldred et al., 2004
- forward propagation of uncertainty Giles, 2008, Ng & Eldred, 2012, Ng & W., 2012, 2014; Peherstorfer et al., 2016
- failure probability estimation
  Bichon et al, 2008; Li & Xiu, 2010; Peherstorfer et al., 2016, Peherstorfer et al., 2017
- optimization under uncertainty Ng, Huynh, W., 2012; Ng & W., 2014, 2016
- statistical inverse problems
  Fox & Christensen, 2008; Efendiev & Hou, 2009; Cui et al., 2014



# Why use multifidelity modeling?

#### Why use a multifidelity formulation?

Reduced model (approximate)

Full model ("truth")

#### Why use a multifidelity formulation?

Reduced model (approximate)

Full model ("truth")

Computationally cheap(er)

Computationally expensive



- Replace full model with reduced model and solve {opt, UQ, inverse}
- Propagate error estimates on forward predictions to determine error in {opt, UQ, inverse} solutions (may be non-trivial)



- {opt, UQ, inverse}
- Hope for the best



• Trade computational cost for the ability to place guarantees on the solution of {opt, UQ, inverse}



# Multifidelity Monte Carlo (MFMC)

Efficient uncertainty propagation leveraging multiple models

Ng & W., **Multifidelity approaches for optimization under uncertainty**, *IJNME*, 2014 Peherstorfer, W. & Gunzburger, **Optimal model management for multifidelity Monte Carlo estimation**, *S/SC*, 2016

### Estimating Qol statistics

via Monte Carlo sampling

- uncertain **input**  $z \in \mathcal{Z}$
- **output** quantity of interest  $y \in \mathcal{Y}$
- high-fidelity **model**   $f^{(1)}: \mathcal{Z} \rightarrow \mathcal{Y}$ with cost  $w_1 > 0$  ("truth")



• Example: expected value  $s = E[f^{(1)}(Z)]$ 



• Monte Carlo estimator for *s* using *n* realizations  $z_1, ..., z_n$  of *Z* has costs  $nw_1$ :  $\hat{s} = \bar{y}_n^{(1)} = \frac{1}{n} \sum_{i=1}^n f^{(1)}(z_i)$ 



### Multifidelity Monte Carlo

leveraging multiple approximate models to estimate statistics of the high-fidelity model

- high-fidelity model
  - $f^{(1)}: \mathcal{Z} \rightarrow \mathcal{Y}(\text{"truth"})$
- k-1 surrogate models

 $f^{(2)}, \dots, f^{(k)} \colon \mathcal{Z} \to \mathcal{Y}$ 

- model  $f^{(i)}$  has cost  $w_i$
- $m_i$  evaluations for model *i*, with

 $m_1 \leq m_2 \leq \ldots \leq m_k$ 

- Models do not necessarily form a hierarchy (cf. multi-level Monte Carlo)
  - How to combine models?
  - How to balance evaluations among them?



•

 $f^{(k)}$ 

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### Multifidelity Monte Carlo

leveraging multiple approximate models to estimate statistics of the high-fidelity model Draw  $m_k$  realizations  $z_1, ..., z_{m_k}$  of Z and evaluate  $f^{(i)}$ :  $f^{(i)}(z_1), ..., f^{(i)}(z_{m_i})$ 

 $f^{(2)}$ 

f(k)

Compute mean estimators  $\overline{y}_{m_1}^{(1)}, \dots, \overline{y}_{m_k}^{(k)}$  and  $\overline{y}_{m_1}^{(2)}, \dots, \overline{y}_{m_{k-1}}^{(k)}$ 

• MFMC estimator:



- $\begin{array}{lll} \mbox{MFMC} & \mbox{mean estimate using} & \mbox{mean estimate using} & \mbox{mean estimate} & \mbox{mean estimate} & \mbox{mean estimate} & \mbox{using} \ m_i & \mbox{using} \ m_{i-1} & \mbox{evaluations of} & \m$
- MFMC estimator is unbiased, even with no error bounds for surrogates: E[ŝ] = s

### Multifidelity Monte Carlo

#### General case with k models

Peherstorfer, W., Gunzburger, *SISC*, 2015

MFMC estimator



- The costs of the MFMC estimator are  $c(\hat{s}) = \sum_{i=1}^{k} w_i m_i$
- Distinguishing features of MFMC method:
  - optimal selection of the number of model evaluations  $m_1 \le m_2 \le \dots \le m_k$  and of coefficients  $\alpha_2, \dots, \alpha_k$
  - applicable to general information sources (e.g., any type of surrogate model, database curve fits, etc.)

#### A broad view of multifidelity models

in many outer-loop applications, can exploit past evaluations as a low-fidelity model

Ng & W., *J. Aircraft,* 2015

in optimization under uncertainty, can exploit model correlation over design space

- use  $f^{(1)}(x + \Delta x, z)$  as **surrogate** for  $f^{(1)}(x, z)$ 



- at current design point x<sub>k</sub>
  - Define  $A = f^{(1)}(x_k, z)$
  - Want to compute  $\hat{s}$  as estimator of  $s = \mathbb{E}[A]$
- previously visited design point  $x_{\ell}$  where  $\ell < k$ 
  - Define surrogate as  $C = f^{(1)}(x_{\ell}, z)$
  - Reuse available data:  $\hat{s}_C$  as estimator of  $s_C = \mathbb{E}[C]$  with error  $Var[\hat{s}_C]$

Information Reuse Estimator

# Multifidelity Importance Sampling (MFIS)

Efficient estimation of low probability events, leveraging multiple models

Peherstorfer, Cui, Marzouk, W., Multifidelity importance sampling, CMAME, 2016 Peherstorfer, Kramer, W., Combining multiple surrogate models to accelerate failure probability estimation with expensive high-fidelity models, in review Estimating a failure probability

via Monte Carlo sampling

- uncertain **input**  $z \in \mathcal{Z}$
- **output** quantity of interest  $y \in \mathcal{Y}$
- high-fidelity model  $f^{(1)}: \mathcal{Z} \to \mathcal{Y}$ with cost  $w_1 > 0$  ("truth")



 $f^{(1)}$ 

- define indicator function  $I^{(1)}: \mathbb{Z} \to \mathcal{Y}$  as  $I^{(1)}(z) = \begin{cases} 1, & \text{if } f^{(1)}(z) < 0 & \leftarrow \text{ failure event} \\ 0, & \text{else} \end{cases}$
- random variable Z with probability density p
- goal: estimate failure probability  $P_f = \mathbb{E}_p[I^{(1)}(Z)]$
- Monte Carlo estimation of  $P_f$  using N realizations  $Z_1, \dots, Z_N$ :

$$P_f^{\text{MC}} = \frac{1}{N} \sum_{i=1}^N I^{(1)}(z_i)$$

Estimating a failure probability

via importance sampling

- Importance sampling: create biasing density q that puts more weight on failure events
- Let  $\hat{Z}$  be the corresponding RV
- Introduce the weight function  $w(z) = \frac{p(z)}{q(z)}$
- Reformulate failure probability as  $P_f = \mathbb{E}_p \left[ I^{(1)}(\mathbf{Z}) \right] = \mathbb{E}_q \left[ I^{(1)}(\hat{Z}) w(\hat{Z}) \right]$
- Goal: construct a biasing density q such that  $\operatorname{Var}_{q}\left[I^{(1)}(\hat{Z})w(\hat{Z})\right] < \operatorname{Var}_{p}\left[I^{(1)}(Z)\right]$
- Lower variance means fewer realizations of  $\hat{Z}$  than of Z are necessary to achieve the same MSE  $\rightarrow$  fewer model evaluations



#### Multifidelity importance sampling (MFIS)

with two models

Peherstorfer, Cui, Marzouk, W., *Computer Methods in Applied Mechanics and Engineering*, 2016

- We derive q with surrogate  $f^{(2)}$  , and use  $f^{(1)}$  to estimate  $P_{\!f}$ 
  - Step 1: Construction of biasing distribution ("speedup")
  - Step 2: Estimation of P<sub>f</sub> using q ("establish accuracy guarantees")



Multifidelity importance sampling

Step 1: construction of biasing density

- Draw *many* realizations  $z_1, \ldots, z_N$  of Z (nominal)
- Evaluate surrogate model to obtain outputs

$$f^{(2)}(z_1), \dots, f^{(2)}(z_N)$$

• Fit normal dist. *q* to realizations that correspond to failure

$$\{z_i \mid I^{(2)}(z_i) = 1, i = 1, \dots, N\}$$

- Use Expectation-Maximization (EM) algorithm to fit density
- Derive random variable  $\hat{Z}$  with distribution given by q

Multifidelity importance sampling

Step 2: estimation of failure probability

- Draw  $M \in \mathbb{N}$  realizations  $\hat{z}_1, \dots, \hat{z}_M$  of  $\hat{Z}$  (biasing)
- Evaluate high-fidelity model to obtain outputs

 $f^{(1)}(\hat{z}_1), \dots, f^{(1)}(\hat{z}_M)$ 

- typically have  $M \ll N$ , and therefore fewer high-fidelity model evaluations
- Derive the multifidelity importance sampling (MFIS) estimate

$$P_f^{\text{MFIS}} = \frac{1}{M} \sum_{i=1}^M I^{(1)}(\hat{z}_i) w(\hat{z}_i)$$

• We can show unbiasedness of the MFIS estimator  $P_f = \mathbb{E}_q[P_f^{\text{MFIS}}]$ 

## Mixed MFIS

extending MFIS to multiple models

- Given are k 1 models  $f^{(2)}, \dots, f^{(k)}: \mathcal{Z} \to \mathcal{Y}$
- Approximation qualities of these sources unknown
- Which of these should we use for constructing *q*?
- Our approach: Mixed MFIS
  - Use each surrogate  $f^{(i)}$  to construct a density  $q_i$ , for i = 2, ..., k

 $f^{(1)}$ 

 $f^{(2)}$ 

f(k)

- Sample from all these densities  $q_2, \ldots, q_k$  and combine samples
- Mixed MFIS estimator  $P_f^{\text{Mixed}}$  derived as in [Owen et al, 2000]
- Known that

$$\frac{\operatorname{Var}[P_f^{\operatorname{Mixed}}]}{k-1} \le \min_{i=2,\dots,k} \operatorname{Var}\left[I^{(1)} \frac{p}{q_i}\right]$$

• Our  $P_f^{\text{Mixed}}$  is up to factor k-1 as good as using the surrogate that minimizes variance

#### Example: Locally damaged plate (multiple models)

- Locally damaged plate
- Inputs: nominal thickness, load, two damage parameters
- Inputs uniformly distributed in [0.05, 0.1] x [1, 100] x [0, 0.2] x (0, 0.05]
- QoI: maximum deflection of plate



- Six models available
  - High-fidelity model: FEM, 300 dof

Peherstorfer

& W., 2015

- Reduced model: POD, 10 dof
- Reduced model: POD, 2 dof
- Reduced model: POD, 5 dof
- Data-fit model: linear interpolation, 256 pts
- Support vector machine: 256 pts
- Variance, correlation, runtime estimated from 100 samples

### Locally damaged plate: MFMC

MFMC estimation of mean deflection achieves up to 4 orders of magnitude reduction in computational cost



- Combine high-fidelity + reduced (POD, 10) + data-fit (linear interp, 256)
- Reduced and data-fit model lead to biased estimator, MFMC is unbiased

Locally damaged plate: MFMC mean estimate

Successively add reduced (POD, 10), data-fit (linear interp, 256), and then all others

Adding data-fit model reduces variance, even though data-fit model is poor approximation of high-fidelity model MFMC achieves almost 4 orders of magnitude improvement over standard Monte Carlo simulation with high-fidelity model only.



## Locally damaged plate: MFIS

Estimate the probability that the deflection exceeds a critical value



- Biasing density constructed from  $N = 10^{6}$ realizations
- Using surrogate only leads to large bias
- MFIS leads to unbiased estimate of P<sub>f</sub>
- If ROM available, speedup of up to 10<sup>4</sup>, cf. high-fidelity

## Conclusion

Multifidelity strategies for the outer loop:

leverage approximate models but maintain guarantees on outer-loop result

- Multifidelity Monte Carlo (MFMC): a control variate formulation for estimating means
- Multifidelity Importance Sampling (MFIS): an importance sampling formulation for estimating probabilities
- MFMC extension to estimating variance and sensitivity indices (Qian MS89, MS145)

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